On the Rotation Properties of a Post-explosion Helium-star Companion in **Type Iax Supernovae**

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Abstract

Recent studies have suggested that type Iax supernovae (SNe Iax) are likely to result from a weak deflagration explosion of a Chandrasekhar-mass white dwarf in a binary system with a helium (He)-star companion. Assuming that most SNe Iax are produced from this scenario, in this work we extend our previous work on the threedimensional hydrodynamical simulation of ejecta-companion interaction by taking the orbital and spin velocities of the progenitor system into account. We then follow the post-impact evolution of a surviving He-star companion by using the one-dimensional stellar evolution code MESA. We aim to investigate the post-explosion rotation properties of a He-star companion in SNe Iax. We find that the He-star companion spins down after the impact due to the angular-momentum loss and expansion caused by the mass-stripping and shock heating during the interaction. This leads to the situation where the surface rotational speed of the surviving companion can drop to one-third of its pre-explosion value when it expands to a maximum radius a few years after the impact. Subsequently, the star shrinks and spins up again once the deposited energy is released. This spin-switching feature of the surviving He-star companions of SNe Iax may be useful for the identification of such objects in future observations.

Key words: (stars:) binaries (including multiple): close – methods: numerical – (stars:) supernovae: general

1. Introduction

Most type Ia supernovae (SNe Ia) follow an empirical widthluminosity relation, i.e., the so-called "Phillips relation" (Phillips 1993). These SNe Ia are usually called "normal" SNe Ia. Using normal SNe Ia as a good cosmic distance indicator has led to the discovery of the accelerating expansion of the Universe (Riess et al. 1998; Schmidt et al. 1998; Perlmutter et al. 1999). However, the progenitor models and explosion mechanism of SNe Ia are still unknown. An SN Ia is generally thought to be a thermonuclear explosion of a near-Chandrasekhar-mass or sub-Chandrasekhar-mass white dwarf (WD) through accreting material either from a non-degenerate companion star (i.e., the single-degenerate [SD] model; Whelan & Iben 1973; Han & Podsiadlowski 2004; Liu & Stancliffe 2018, 2020) or another WD (i.e., the double-degenerate model; Iben & Tutukov 1984; Webbink 1984). In the SD model, the non-degenerate companion star could be a main sequence star, a red giant star or a helium (He) star, and the companion star is expected to survive the explosion (e.g., Wheeler et al. 1975; Marietta et al. 2000; Podsiadlowski 2003; Han 2008; Pakmor et al. 2008; Liu et al. 2012, 2013a, 2013b, 2013c, 2021; Pan et al. 2012; Shappee et al. 2013; Boehner et al. 2017; Bauer et al. 2019).

More and more observations have shown that there are subclasses of SNe Ia (e.g., Filippenko et al. 1992a, 1992b; Li et al. 2003). Type Iax supernovae (SNe Iax) are the most common sub-class of SNe Ia (Foley et al. 2013; Liu et al. 2015c). To date, about 50 SNe Iax have been found (e.g., Jha 2017), which contribute around 30% of the total SN Ia birthrates (Li et al. 2003; Foley et al. 2013; White et al. 2015). Recent studies seem to suggest that SNe Iax are produced from the weak deflagration explosion of a near-Chandrasekhar-mass WD in an SD binary system with a He-star companion. For instance, He emission lines have been detected in early-time spectra of two SNe Iax, i.e., SN 2004cs and SN 2007J (Rajala et al. 2005; Foley et al. 2009, 2013). A possible progenitor He-star companion has been detected in the pre-explosion images of an SN Iax SN 2012Z (McCully et al. 2014; Liu et al. 2015b). Most SNe Iax have been found in late-type, star-forming galaxies (e.g., Foley et al. 2010, 2013), suggesting short delay times for SNe Iax that are consistent with the theoretical predictions of the progenitor systems composed of a WD and a He-star companion (e.g., Foley et al. 2013; Lyman et al. 2013, 2018; White et al. 2015; Takaro et al. 2020; Liu et al. 2015a). In addition, recent studies have shown that the weak deflagration explosion of a near-Chandrasekhar-mass WD



seems to be able to well reproduce the observational features of SNe Iax (e.g., Branch et al. 2004; Jordan et al. 2012; Kromer et al. 2013; Fink et al. 2014). However, other possible models such as the pulsational delayed detonation explosion model have also been suggested for SNe Iax (Hoeflich et al. 1995; Meng & Podsiadlowski 2014; Stritzinger et al. 2015).

In our previous work of Zeng et al. (2020), by assuming that SNe Iax are caused by weak deflagration explosions of progenitor systems composed of a WD and a He-star companion, we investigated the details of ejecta-companion interaction by performing three-dimensional (3D) hydrodynamical simulations with smoothed particle hydrodynamics (SPH; Gingold & Monaghan 1977; Lucy 1977) code STELLAR GADGET (Pakmor et al. 2012). We find that a small amount of He mass ($\sim 0.4\%$ of companion masses) is stripped off from the companion surface during the ejecta-companion interaction (Zeng et al. 2020), which provides an explanation for the nondetection of He lines cased by the swept-up He-rich companion material in late-time spectra of SNe Iax (e.g., Foley et al. 2013, 2016; Magee et al. 2019; Jacobson-Galán et al. 2019; Tucker et al. 2020). Furthermore, we have also followed the long-term evolution of the surviving He-star companions by using the one-dimensional (1D) stellar evolution code MESA (Paxton et al. 2018) to predict their post-explosion properties (Y. Zeng et al. 2022, in preparation). However, in these previous studies we did not consider the orbital and spin velocities of the progenitor system in our 3D hydrodynamical impact simulations, leading to the situation that we could not completely study the post-impact rotation properties of a surviving He-star companion. It has been suggested that the rotation of a companion star can be significantly reduced due to the angularmomentum loss and significant expansion caused by the ejectacompanion interaction (Meng & Yang 2011; Liu et al. 2013b; Liu & Stancliffe 2017; Liu et al. 2022; Pan et al. 2012, 2013). For example, Tycho G has been suggested to be a candidate of the surviving companion star in SN 1572 (i.e., Tycho's SN) because of its peculiar spatial velocity (Ruiz-Lapuente et al. 2004). However, Kerzendorf et al. (2009) found that Tycho G has a small rotational velocity of 8 km s^{-1} (Kerzendorf et al. 2014), which is much slower than the predicted spin velocities of companion stars at the moment of SN explosion (Han 2008). By investigating the post-impact rotation properties of the surviving companions, Pan et al. (2012) suggested that one cannot rule out Tycho G as the candidate of the surviving companion star of the Tycho SN Ia only based on its small rotational velocity because of the angular-momentum loss and significant expansion of the star due to the interaction can cause its rotational velocity to drop significantly after the impact (Pan et al. 2012; Liu et al. 2013b, 2022). Furthermore, the postimpact rotation properties of an SN Ia's surviving companion star have been thought to be helpful for the identification of such objects in nearby SN remnants (SNRs).

In this work, by adopting the same progenitor and explosion models for SNe Iax that were used in Zeng et al. (2020), we extend our previous 3D hydrodynamical simulations of ejectacompanion interaction by taking the orbital and spin velocities of the progenitor system into account. The main goal of this work is to investigate the post-impact rotation properties of a surviving He-star companion in SNe Iax. In Section 2, we briefly describe our methods and models. The results of evolution of our surviving He-star companion model are given in Section 3, including evolutionary tracks, post-impact rotation properties and a comparison with the non-rotating model. Finally, we provide a summary and conclusion in Section 4.

2. Numerical Methods

2.1. Ejecta-companion Interaction

To perform a 3D hydrodynamical simulation of ejectacompanion interaction, we employ the STELLAR GADGET code (Pakmor et al. 2012). The initial models and basic assumptions are set to be the same as those in our previous study (for the details, see Section 2 of Zeng et al. 2020) except that the orbital and spin velocities of the progenitor system are considered in the present work. Therefore, we only briefly describe them as follows.

Our initial He-star companion model at the moment of SN Ia explosion was constructed by following 1D detailed binary evolution of a progenitor system composed of a $1.10 M_{\odot}$ WD and a $1.55 M_{\odot}$ He-star donor, in which the binary system has an initial orbital period of ~ 0.05 day. The WD accretes He-rich material from the companion star through Roche-lobe overflow to increase its mass to $1.38 M_{\odot}$. At that point, we assume that the WD explodes as an SN Iax, and we take out the He-star companion model at this moment as the input of our subsequent 3D impact simulation (for a detailed description, see Liu et al. 2013c). In addition, we assume that the rotation of the He-star companion is synchronized with its orbital motion at the time of SN Iax explosion due to strong tidal interaction during the pre-explosion mass-transfer phase, $\omega_{\rm rot} = \omega_{\rm orb}$, where $\omega_{\rm rot}$ and $\omega_{\rm orb}$ are the rotational and orbital angular velocities of the He-star companion, respectively. Based on our 1D full binary evolution calculation, the binary system at the moment of SN Ia explosion has a separation of $A = 5.16 \times 10^{10}$ cm, a WD mass of $M_{\rm WD} = 1.38 M_{\odot}$, a companion mass of $M_2 = 1.24 M_{\odot}$, a companion radius of $R_2 = 1.91 \times 10^{10}$ cm and a corresponding angular velocity of $\omega_{\rm rot} = 1.59 \times 10^{-3}$ rad s⁻¹ (which leads to a companion rotational velocity of ~ 301 km s⁻¹). We use the so-called "N5def model" to represent an SN Iax explosion in our impact simulations because this model has been found to well reproduce the observational features of a typical SN Iax such as SN 2005hk (Kromer et al. 2013; Fink et al. 2014). In the N5def model, the weak deflagration explosion does not

completely disintegrate the entire Chandrasekhar-mass WD (1.40 M_{\odot}), leaving a bound remnant WD of about 1.03 M_{\odot} after the explosion (Kromer et al. 2013; Fink et al. 2014).

We use Cartesian coordinates in our 3D impact simulations. The x-y plane is chosen as the orbital plane of the system, and the positive direction of the z-axis is the direction of spin of the binary system. We add the initial orbital and spin velocities of each SPH particle by assuming that the binary system is synchronized. Therefore, the initial orbital and spin velocities of a particle *i* are given by $\mathbf{v}_i = \boldsymbol{\omega} \times (\mathbf{r}_i - \mathbf{r}_c)$, where \mathbf{r}_i is the position of the particle *i*, \mathbf{r}_c is the position of the center of mass of the binary system and ω is the angular velocity, $\omega = \omega_{\rm rot} = \omega_{\rm orb}$. Similar to our previous work Zeng et al. (2020), in this work we also consider mass-stripping due to conservation of angular momentum and the shock heating and energy deposition into the companion star in 3D impact simulations. The 3D simulation is run for about 5000 s after the explosion, at which time the unbound companion masses reach a stable value.

2.2. From 3D to 1D

To present the post-explosion properties of a surviving companion star for their identifications in historical SNRs, we need to follow post-explosion evolution of a surviving companion star for a long timescale up to a few thousand years. However, it is really difficult to do that by tracing our 3D hydrodynamical simulations for such long timescale because of the very expensive computational cost. We therefore map the outcome of 3D SPH simulation into the 1D stellar evolution code MESA (Paxton et al. 2011, 2013, 2015, 2018, 2019) to follow the post-impact evolution of a surviving He-star companion in an SN Iax for a long timescale up to about 10^5 yr until it has relaxed back into thermal equilibrium (see also Liu & Zeng 2021; Liu et al. 2021).

Whether or not the progenitor binary system could be destroyed after the SN explosion strongly depends on the kick velocity of the bound WD remnant because the companion star receives a small kick velocity and only a small amount of companion mass is stripped off during the interaction. However, the kick velocity of the bound remnant predicted by current studies is quite uncertain. For instance, Fink et al. (2014) obtained a small kick velocity of $\sim 36 \text{ km s}^{-1}$, but Jordan et al. (2012) predicted a large kick velocity up to $\sim 520 \text{ km s}^{-1}$. We refer to Liu et al. (2013a, see their Section 5.4) for a detailed discussion on the fate of the progenitor binary system in this scenario. In this work, we simply assume that the binary system is destroyed after the explosion, and we therefore do not include the bound WD remnant into our 3D impact simulations and the post-impact evolution calculations of surviving He-star companions. The details of the post-explosion evolution with the inclusion of the bound WD remnant should be addressed in future work.

Following the method of Liu & Zeng (2021, see their Section 2), the angle-averaged radial profiles of internal energy, chemical composition and angular momentum of the surviving He-star companion at the end of our 3D SPH impact simulations are used as inputs of relaxation routines in MESA (Paxton et al. 2018, see appendix B) to construct a starting model for its subsequent 1D long-term post-impact evolution (see also Liu et al. 2021, 2022). Figure 1 shows a comparison of density distributions of our surviving He-star companion at the pre-explosion phase and at the end of our 3D hydrodynamical simulations. In Figure 2, we plot the 1D radial profiles of density, specific internal energy and specific angular momentum of our surviving He-star companion at the preexplosion phase, the end of 3D impact simulation and the starting phase of the subsequent long-term evolution by MESA calculation.

3. Results and Discussions

In this section, we present the results of long-term postexplosion evolution of a surviving He-star companion with 1D MESA calculation, including the post-explosion evolutionary tracks of a star in the Hertzsprung-Russell (HR) diagram and its rotational properties. We also compare the results with those of a non-rotating model in our previous study of Y. Zeng et al. (in preparation). Our main results are summarized in Table 1.

3.1. Post-explosion Evolutionary Tracks

Based on our 3D impact simulation, we find that the inclusion of the orbital and spin velocities of the progenitor system does not significantly affect the total stripped He masses and the kick velocity received by the star during the ejecta-companion interaction. This is because the orbital (\sim 430 km s⁻¹) and spin (\sim 301 km s⁻¹) velocities of the companion star are one order of magnitude lower than the typical velocity of SN ejecta of \sim 7000 km s⁻¹. We find that about 0.4% of companion mass is removed by the SN explosion, and the star receives a kick velocity of \sim 8 km s⁻¹ in both the non-rotating and rotating model. At the end of 3D SPH impact simulation, the companion star is out of thermal equilibrium because of the mass-stripping and shock heating during the interaction (see Figure 1).

In Figure 3, we depict the post-explosion luminosity, temperature, photosphere radius and surface gravity of our surviving He-star companion as functions of time. In addition, its evolutionary track in the HR diagram is presented in Figure 4. The surviving He-star companion significantly expands after the impact due to the release of energy deposition by the shock heating during the ejecta-companion interaction. About one year after the explosion, the star reaches a maximum luminosity of $1.5 \times 10^4 L_{\odot}$ when it expands to a maximum radius of $1.2 R_{\odot}$. The star starts to shrink and relax back into its thermal equilibrium as the deposited energy radiates away, and

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Figure 1. Density distributions of our $1.24 M_{\odot}$ He-star companion model in the orbital plane at t = 0 s, 20 s, 50 s, 250 s, 500 s and 5000 s of our 3D SPH hydrodynamical impact simulation. The color scale indicates the logarithm of the mass density.



Figure 2. Radial profiles of density (ρ , left panel), specific internal energy (*E*, middle panel) and specific angular momentum (*j*, right panel) of our He-star companion model at the beginning (red dashed line) and the end of 3D SPH impact simulation (orange solid line). The corresponding profiles of the starting model for MESA post-explosion calculation are also drawn in blue dash-dotted lines. Here, M_r is the enclosed mass within a sphere of radius *r* and M_* is the total mass of the star.

Table 1 Results of our Simulations								
Model	$\Delta M/M_2$ (%)	$V_{ m kick}$ $(m km \ m s^{-1})$	$\frac{E_{\rm inj}}{(10^{48}{\rm erg})}$	d (M_r/M_*)	$\log L^{ m peak} \ (L_{\odot})$	$\frac{\log T_{\rm eff}^{\rm peak}}{\rm (K)}$	$R^{ m peak}$ (R_{\odot})	t ^{peak} (yr)
Non-rotating Rotating	0.4 0.4	7.6 8.5	3.78 3.89	0.995 0.992	4.16 4.18	4.86 4.81	0.84 1.19	0.95 1.10

Note. ΔM , V_{kick} , E_{inj} and d are the amount of stripped He mass, kick velocity, total deposited energy and depth of energy deposition obtained from our 3D impact simulation respectively; L^{peak} , log $T_{\text{eff}}^{\text{peak}}$ and R^{peak} respectively represent the maximum luminosity, effective temperature and radius of the star during its thermal reequilibration phase; t^{peak} gives the time at the maximum luminosity.

it appears as an O-type hot subdwarf (sdO) star when it has reestablished its thermal equilibrium at about a few 1000 yr. After that, the star keeps evolving by following a quite similar evolutionary track of a non-impacted He-star with the same mass. This indicates that it would be more difficult to successfully identify the surviving He-star companions after they have relaxed back into thermal equilibrium about a few thousand years after the explosion, because their post-impact evolutionary tracks are almost identical to those of normal Hestars at this late-time phase. We therefore conclude that the identification of the surviving He-star companions of SNe Iax is more likely to be successful in young nearby SNRs.

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For comparison, the corresponding results of the nonrotating model obtained from our previous work of Zeng et al. (in preparation) are also drawn in red dashed lines in Figure 3. These differences between rotating and non-rotating model are caused by the amount and depth of energy deposition, and the centrifugal force due to the spin. The depth of energy deposition in the rotating model (which is found to be at $M_r/M_* \sim 0.992$, where M_r is the enclosed mass within a sphere of radius r, and M_* is the total mass of the star) is slightly deeper than that of the non-rotating model (at $M_r/M_* \sim 0.995$), which leads to the non-rotating model taking a slightly shorter timescale to radiate away the deposited energy. In addition, we find a slightly higher amount of energy deposition (i.e., 3.89×10^{48} erg) in the rotating model than that of the nonrotating model (i.e., 3.78×10^{48} erg), which may be caused by a slightly bigger cross-sectional area in the rotating model due to its motion. Compared with the non-rotating model, the centrifugal force and a higher energy deposition in the rotating model make its photosphere expand more as what has been observed in Figure 3.

3.2. Post-explosion Surface Rotational Speed

At the beginning of our 3D impact simulations, the companion star is spherically symmetric (see left-panel of Figure 1), and its initial rotation was set up to be a rigid-body



Figure 3. Time evolution of the post-impact luminosity, temperature, radius and surface gravity of the rotating surviving He companion model (red dashed line). For comparison, the results of the post-impact evolution of the corresponding non-rotating model are drawn in black solid lines.



Figure 4. Post-impact evolutionary tracks of the rotating companion model in the HR diagram (red dashed lines) and surface gravity vs. temperature diagram (blue dash-dotted lines). For comparison, the results of the corresponding non-rotating model are also drawn in red solid and blue dotted lines.



Figure 5. Radial profiles of the angular velocity of the pre- (red dashed line) and post- (orange solid line) explosion of the He-star companions. Note that the x-axis is normalized to the radius of the He-star companion (R_*).

rotation. As displayed in Figure 5, the entire star has the same angular velocity from the center to the surface, and the rotational velocity increases linearly with radius. After the impact, the He-star companion does not rotate as a rigid body (orange solid line in Figure 5), and some differential rotational features appears. If the He-star companion has an initial magnetic field, the differential rotational features might enlarge the magnetic field (Spruit 2002). We find that about 2% of initial angular momentum of the companion star is lost because about 0.4% of its mass is removed during the interaction at the end of our impact simulation. Meanwhile, the companion radius increases by a factor of 2.5 to reach ~0.68 R_{\odot} due to the shock heating. This leads to the surface rotational velocity of the star dropping to ~180 km s⁻¹ at the end of our impact simulation from its pre-explosion value of ~ 301 km s⁻¹.

In Figure 6, we show the post-impact evolution of the surface rotational speed and angular velocity of the surviving He-star companion from our MESA calculation. As the star expands, its surface rotation keeps decreasing and reaches the minimum value of $\sim 100 \text{ km s}^{-1}$ (which is about 1/3 of its preimpact value) when the star expands to a maximum radius a few years after the impact. After that, the star starts to shrink as the deposited energy is radiated away, leading to the star spinning up again. About 10^2 yr after the impact, it becomes a fast rotator again and has a surface rotational speed of about 300 km s^{-1} , and the rate of change in surface rotational speed ($\delta V_{rot}/\delta t$) is close to zero (see the top and middle panels of Figure 6). We therefore conclude that this rotation-switching feature within a few years may provide a useful way to identify the surviving He-star companions of SNe Iax in future observations.

The He-star companions are expected to have the rotational speeds of $140-380 \text{ km s}^{-1}$ at the moment of SN explosion based on binary population synthesis calculations for the WD + He-star channel of SNe Ia (Wang & Han 2009), which is slower than the typical velocity of SN ejecta of \sim 7000 km s⁻¹ by one order of magnitude. Therefore, we do not expect that the inclusion of the rotational speed of a companion star would significantly affect the results of the ejecta-companion interaction such as the total stripped He mass, the kick velocity, and the amount and depth of energy deposition, compared with those of the non-rotating model. In addition, the fastest spinning companion star in the WD + Hestar channel has a rotational velocity of 380 km s^{-1} , which is not significantly faster than our model (300 km s^{-1}) in this work. We therefore do not expect that the post-impact properties of our rotating model would change significantly if it spins with a bit higher velocity of 380 km s^{-1} . For the slowest spinning model, we expect that it would have similar post-impact properties with our non-rotating model. However, we expect that various spin speeds would cause different centrifugal forces and thus lead to the star having a slightly larger/smaller radius compared with that of the rotating model in this work. Liu et al. (2013b) find that the post-explosion rotational speeds are scaled linearly with the pre-explosion rotational speeds for surviving main-sequence stars. If we



Figure 6. Post-impact evolution of the surface rotational speed (V_{rot} , top-panel), the rate of change of surface rotational speed ($\delta V_{rot}/\delta t$, middle-panel) and the surface angular velocity (ω , bottom-panel) of the surviving He-star companion from our MESA calculations. For comparison, the corresponding critical rotational and surface angular velocities are also drawn in dash-dotted lines. The *x*-axis gives the evolutionary time of a surviving He-star companion since the end of our 3D impact simulations (~5000 s). For better visibility, the evolution before 10^{-2} yr is not shown because no significant difference is observed there.

simply assume that such a relation still holds for surviving Hestar companions in this work, we could roughly estimate that the rotational velocities of the surviving He-star companions could drop to 47-127 km s⁻¹ after the impact.

4. Summary and Conclusion

In this work, we have performed a 3D hydrodynamical simulation of the interaction of SN ejecta with a He-star companion with the SPH code STELLAR GADGET (Pakmor et al. 2012) by directly adopting the He-star companion model and explosion model used by Zeng et al. (2020). However, the rotation of the companion star and orbital motion of the binary system are also taken into account in the 3D impact simulation

of this work. We further follow the long-term post-impact evolution of the surviving companion star by using 1D stellar evolution code MESA (Paxton et al. 2011, 2013, 2015, 2018, 2019). We aim to focus on exploring the post-impact rotation evolution of the surviving He-star companions of SNe Iax. Our results and conclusions are summarized as follows.

- 1. We find that about 0.4% of companion masses are removed by SN Ia impact during the ejecta-companion interaction, and the He-star companion receives a kick velocity of $\sim 8 \text{ km s}^{-1}$. These results are comparable to those of the non-rotating model of Zeng et al. (2020).
- 2. We find that the depth of energy deposition due to shock heating during the interaction in the rotating model is

about $M_{\rm r}/M_{*} \sim 0.992$, which is slightly deeper than that of the non-rotating model of $M_r/M_* \sim 0.995$. In addition, the amount of energy deposition in the rotating model (i.e., 3.89×10^{48} erg) is higher than that of the nonrotating model (i.e., 3.78×10^{48} erg). A higher amount of energy deposition and the centrifugal force in the rotating model make its photosphere expand more compared with the non-rotating model (Figure 3).

- 3. About 2% of initial angular momentum of the companion star is lost because about 0.4% of its mass is removed by the SN Ia impact. In addition, the companion star significantly puffs up due to the shock heating. As a result, the surface rotational velocity of the companion star drops to $\sim 180 \,\mathrm{km \, s^{-1}}$ at the end of our impact simulation from its pre-explosion value of $\sim 301 \text{ km s}^{-1}$.
- 4. The surface rotational velocity of the surviving He-star companion keeps decreasing as it expands, and it reaches the minimum value of $\sim 100 \text{ km s}^{-1}$ when the star expands to a maximum radius at about a few years after the impact. Subsequently, the star starts to shrink as the deposited energy is radiated away, leading to the surviving He-star companion spinning up again. Our results suggest that the rotation of the surviving He-star companions of SNe Iax could significantly drop, although they were originally fast-rotating at the moment of SN Ia explosion.
- 5. We find that the surviving He-star companions of SNe Iax experience the spin-down and spin-up phases within a few years after the explosion. This peculiar rotationswitching feature would be useful for the identification of surviving He-star companions of SNe Iax in future observations.

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