Research in **A**stronomy and **A**strophysics

Generating a radioheliograph image from SDO/AIA data with the machine learning method

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Received 2020 May 3; accepted 2020 June 23

Abstract Radioheliograph images are essential for the study of solar short term activities and long term variations, while the continuity and granularity of radioheliograph data are not so ideal, due to the short visible time of the Sun and the complex electron-magnetic environment near the ground-based radio telescope. In this work, we develop a multi-channel input single-channel output neural network, which can generate radioheliograph image in microwave band from the Extreme Ultra-violet (EUV) observation of the Atmospheric Imaging Assembly (AIA) on board the Solar Dynamic Observatory (SDO). The neural network is trained with nearly 8 years of data of Nobeyama Radioheliograph image is in good consistency with the well-calibrated NoRH observation. SDO/AIA provides solar atmosphere images in multiple EUV wavelengths every 12 seconds from space, so the present model can fill the vacancy of limited observation time of microwave radioheliograph, and support further study of the relationship between the microwave and EUV emission.

Key words: Sun: radio radiation - methods: observational - methods: data analysis

1 INTRODUCTION

Microwave radioheliograph data are essential for the diagnosis of the solar atmosphere and the surveillance of solar activity (Shibasaki 2013; Huang & Nakajima 2009; Mei et al. 2017; Tan et al. 2016). The quality and the continuity of the radioheliograph data is not as good as optical observation. The optical devices, for example, the Extreme Ultra-violet (EUV) observatory, can be launched into space, because of relatively small aperture comparing to the radioheliograph array (Lemen et al. 2011; Sandel et al. 2000; Wülser et al. 2004). The spacecraft can provide more continuous observation for the Sun, compared with the ground-based observatory which cannot observe the Sun for all-time due to the limited visible duration of the Sun. Moreover, the groundbased radio devices are more liable to be affected by the complex electromagnetic environment, which will cause calibration problems. In this work, we intend to develop a machine-learning program which can learn the patterns of solar EUV images and the well-calibrated radioheliograph images, we then produce the radioheliograph image from EUV data to provide full-time microwave heliograph.

Conventionally, the modeling and reconstruction of radioheliograph image from EUV observation are based on the differential emission measure (DEM) method. Both the EUV radiation and radio emission come from the thermal electrons in the corona during non-flaring time. The corona electron density (n_e) and temperature (T_e) distribution can be obtained by DEM inversion of the multi-channel EUV emission (Pallavicini et al. 1981; Cheng et al. 2012), then the radio brightness temperature can be derived from n_e and T_e distribution with a given emission mechanism. Zhang et al. (2001) used thermal bremsstrahlung emission mechanism to predict the microwave heliograph image with the EUV data of EIT (Extreme-ultraviolet Imaging Telescope) on-board SOHO (Solar and Heliospheric Observatory), and find that the predicted radio flux is systematically larger than that observed by a factor of 2.0. Meanwhile, Alissandrakis et al. (2019) modeled the sunspot-associated microwave emission based on the gyro-resonance emission mechanism with potential

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extrapolations of the photospheric magnetic field, in which the DEM was inverted from the EUV image of Atmospheric Imaging Assembly (AIA) on-board the Solar Dynamics Observatory (SDO) (Lemen et al. 2011). More recently, Li et al. (2020) find that the predicted radio flux is closer to the observations in the case that includes the contribution of plasma with temperatures above 3 MK than in the case of only involving low temperature plasma, and confirmed the thermal origin of the quiet corona radio emission. The predicted value of the DEM method depends on the physics model, including the derivation of n_e , T_e and magnetic field, and the emission mechanism.

The observed radio flux in the line of sight is a convoluted result of the wave excitation and the wave propagation process (Shibasaki et al. 2011; Tan et al. 2015). The brightness temperature at a given position is affected by both local conditions and the large-scale coronal structures. This creates some difficulty to the modeling of radio emission from EUV data with a pixel to pixel translation (such as in the DEM method), while the machine-learning method with a convolutional neural network (CNN) has the advantage of connecting areas to pixels.

The machine-learning method has recently been applied to solar physics (Bobra & Mason 2019). Ma et al. (2017) used a neural network based on the multimodal learning architecture to classify the existence of the radio burst. Li & Zhu (2013) used a multi-layer model to predict the solar flare based on sequential sunspot data. Xu et al. (2019) used long short term memory (LSTM) network to classify multiple types of the solar radio spectrum. As a large set of image data, SDO data is suitable for various purposes of machine learning work. Neural networks like CNN and the generative adversarial networks (GAN) can be used for data generation and competition. For examples, Szenicer et al. (2019) used a combined CNN to produce the EUV irradiance map from SDO/AIA image, Kim et al. (2019) applied GAN to generate the magnet flux distribution of the Sun from SDO/AIA image, and Xu et al. (2020) used the GAN for the de-convolution of the solar radio image.

In this work, we proposed a model for radioheliograph reconstruction from SDO/AIA multi-channel EUV images, using the machine-learning method based on a multi-channel input single-channel output neural network. In Section 2, the dataset, the architecture and training process of the neural network is elaborated. In Section 3, we present the statistical results and some representative cases to show the reliability of the trained neural network. In Section 4, we summarize the result, and discuss the meaning of the result and further usage of this method.

2 METHOD

2.1 Dataset

In this work, the microwave image data we use is from the Nobeyama Radioheliograph (https: //solar.nro.nao.ac.jp/norh/html/daily/,

NoRH) (Nakajima et al. 1994). The EUV image data we use is provided by SDO/AIA (Lemen et al. 2011), which is downloaded with sunpy (Mumford et al. 2015) from Virtual Solar Observatory (https://sdac.virtualsolar.org/cgi/search,

VSO). The dataset we used is the 17 GHz radioheliograph image at noon of Nobeyama local time from January 2011 to September 2018, and the SDO/AIA image of five wavelengths: 171, 193, 211, 304, 335 Å for the corresponding time. The original size of the EUV image from SDO/AIA is (4096, 4096) pixels, while the original size of radio heliograph image from NoRH is (512, 512) pixels. For the convenience of further training, the original data is feed to the following prepossessing steps:

- 1. Shift the solar center to the center of the image.
- 2. Crop the image to 1.1 times of the solar radius.
- 3. Re-sample the EUV image into the size of (512, 512) pixels.
- Modify the NaN (not a number) points and minus values in the data to zero.
- 5. Normalize the brightness temperature with 10^4 K to avoid the byte overflow of float-type number during the training.
- 6. Save as Numpy form (.npy) file format for faster load.
- Manually select and mark the corrupted or not wellcalibrated data frames, which would be sheltered from the training.

The final size of the total dataset is about 18 GB with 2622 data frames, and the data is stored in RAMDisk to accelerate the data loading in the training and testing process.

2.2 Neural Network Architecture

We used a multi-input single-output four level U-Net (abbreviated as MISO-UNet) to produce the microwave heliograph data. The detailed architecture is shown in Figure 1. This MISO-UNet has 3.35×10^6 parameters, the size of the trained parameter-set file is 12.79 MB. The loss-function is the Mean Square Error (MSE) between the observed NoRH image (labeled as OBS) and the neural network generated image (labeled as GEN):

$$Loss = \frac{\sum_{i} (I_{OBS,i} - I_{GEN,i})^2}{N_{pix}},$$
 (1)

where $I_{\text{OBS},i}$ and $I_{\text{GEN},i}$ are the normalized brightness temperature of the *i*th pixel in the observed image and



Fig.1 The architecture of the neural network, where the *arrows* represent the data flow direction, the *white blocks* represent the nodes in the data flow, and the size of each node is marked beneath the block.

the generated image, respectively. The value of brightness temperature is normalized with 10^4 K. N_{pix} is the total number of pixel in the training data. The neural network is implemented with PyTorch (Paszke et al. 2017, 2019), an open source machine learning library. The source code of the data processing and neural network is available online¹.

2.3 Training

We randomly selected out 235 frames as the test set, which are sheltered from the training process. The rest 2387 frames of EUV-radio data is used for the training. The training of 8000 epochs took 94 hours on a single node with four Nvidia Titan Xp GPUs.

The image pattern of radio heliograph is highly related to observation time or the sequence index. There are more active regions at solar high year, while the radio heliograph of solar low year is more similar to pure disk. Consequently, the sequence index of the data frame also directly contains the information of radio heliograph image. For a better learning of the relation between EUV and radio heliograph, we need to intermingle the dataset, so that the neural network is not fed with the information of data order. During the training process, the data frames are shuffled in each epoch.

The converged value of the loss-function is about 7×10^{-4} , corresponding to about 300 K in brightness temperature.

3 RESULTS

After the training process, the trained parameter-set can be loaded into the MISO-UNet model for the production of radio heliograph image. We use the data frames from the test set to verify the reliability of the trained model. It is found that the neural network generated image is well consistent with the observed one. Figure 2 shows three representative cases from the test-set as examples for the comparison of the observed radio images and the neural network generated ones in detail. From left to right, the first column is a case in solar high year (Case 1), where multiple active regions can be seen on the solar surface. The second column represents a case in solar low year (Case 2). The third column represents a case of bad observation (Case 3), mainly from the radio-frequency interference of the complex electromagnetic environments.

The linear fit result of Case 1 and Case 2 is close to y = x, and the correlation value is close to 1.0. To exclude the dark area outside the solar disk in NoRH observation, we only consider the pixels with brightness temperature greater than 1000 K in both GEN and OBS in the statistical investigation. The results indicate that the flux intensity of the generated image and the observed image are well correlated except the observation is corrupt (as in Case 3 shown in the third column of Fig. 2). Moreover, from the first case, we selected three regions to show the detailed comparison of an active region, a quiet region, and a flare, which are marked as blue, red, and green box in the first column of Figure 2. Figure 3 shows the detailed zoom in of the comparison. From the comparison of the GEN and OBS of the quiet region, one can see regular spaced stripe structures in OBS, which are not visible in GEN. For the structure and shape of the active region, GEN and OBS are generally consistent with each other. However, the flare region is not well reconstructed by this method, and the generated brightness temperature is much lower than the observed value as shown in the third column of Figure 3.

Figure 4 shows the histogram distribution of the linear fit slope a, the relative error (re), and the correlation coefficient (cc) between GEN and OBS for the test data set. It is found that ninety percent of the linear fit slope

¹ https://github.com/Pjer-zhang/NorhBot



Fig. 2 Three cases of comparing the observed image and neural network generated image and the corresponding statics. These three cases are not included in the training dataset. The date-time of the image is marked on the top-right corner of the image. The top row is the observed image, the middle row is the generated image using 5-channel EUV data. The bottom row shows the correlation of the observed data and the generated data, where the *x*-axis is the observed brightness temperature, the *y*-axis is the generated brightness temperature, the color indicates the number of pixels with corresponding generated and observed brightness temperature, the *red line* marks the reference line of *x* equals *y*, the *black dashed line* indicates the linear fit result y = ax + b. The linear fit result and the correlation between the observed and generated flux are labeled in each panel of the bottom row.

falls in the range 0.80 < a < 1.02, with an average value of 0.91. The average value of *re* is 0.09, and for 90% of the test frames, *re* is less than 0.1. The average value of *cc* is 0.94, and for 90% of the test frames, *cc* is above 0.91. By inspecting every frame of the test cases, we find that the frames with a < 0.8, cc < 0.9, or re > 0.1 are mostly embedded with a flare-like bright region.

4 CONCLUSIONS AND DISCUSSION

This work proposed a model to reconstruct radioheliograph image from EUV image with a machine learning method based on MISO-UNet. The model generated radio image is in good consistent with the NoRH observed image at 17 GHz, which indicates that the EUV emission and the radio emission has a strong inner relation. We inspected the image details of the generated images compared with the observation. As shown in Figure 3, for quiet region there are regular spaced strips in the observed image, which does not appear in the generated images. We suppose the reason is that, the regular strips in the observation may be due to the instrumental artifacts, which is arbitrary for different image. The training process learns the pattern between the EUV and radioheliograph image, the arbitrary information cannot be assimilated by the model. The structures of the



Fig. 3 The zoom-in comparison of the observed and MISO-UNet generated image. These three columns from left to right present the results for a quiet region, an active region, and a flare, respectively. These there regions are marked as *blue*, *red* and *green box* in Fig. 2, respectively. Note that the color-scale is re-adjusted to show the difference.

active region are well reconstructed. The flux of the flare region is not well reconstructed. On one hand, this is due to the unbalanced sample distribution of the data-set, because the flare is rare compared to the active region and quiet Sun. On the other hand, the radio emission at flare time is mainly produced by non-thermal electrons, while the nonflare emission is coming from the thermal electrons. The bad prediction result of the flare region may be improved by including more data-frames with flare in the future work. Comparing with the DEM method, we can have higher precision of brightness temperature prediction with the machine learning method. The correlation of machine learning prediction is above 0.8 with an average value of 0.94 for the test cases, and the linear fit for the flux intensity of OBS and GEN is also much closer to y = xthan the DEM prediction results (Zhang et al. 2001; Li et al. 2020). This may be partially due to the uncertainty of the DEM inversion and the emission mechanism assumed in the prediction. Either thermal bremsstrahlung emission or gyro-resonance radiation is assumed in the modeling with DEM method, while the quiet microwave emission is a mixture of the two mechanisms (Shibasaki et al. 2011).

In addition, the DEM method of the radio flux estimation is a pixel-to-pixel operation, the final brightness temperature only considers the EUV flux of the pixel with the same coordinate in the sky plane. While in the MISO-UNet, the final brightness temperature value of any pixel considers not only the influence of the pixel with the same coordinate, but also the effects of surrounding large scale structures. The large and small scale features of all EUV channels spread though the neural network to the final brightness temperature by convolution operations. In fact, the observed radio flux is a convoluted results of the wave excitation and propagation process. The brightness temperature of a given position is affected by both local conditions and the large-scale coronal structures, such as coronal holes, loop systems, and streamers etc (Shibasaki et al. 2011). It is important to consider the nearby structures when deriving the observed radio emission of a given point. The MISO-UNet is suitable for the prediction of microwave emission map because it has the advantage of connecting areas to pixels. However, it needs to note that the machine learning method can only predict the data of the trained frequency which is fed to the training process, and the DEM method can calculate the brightness temperature of the quiet Sun at different radio frequencies.

Finally, NoRH was shut down on 2020 March 31 after continuously observing the full Sun for about eight hours every day in the past three decades. The trained MISO-UNet can produce radio heliograph image when SDO/AIA data is available. The present work is not only helpful to correct the bad observation data of NoRH due to electromagnetic interference and so on but may also provide a virtual interferometric microwave observation



Fig. 4 The histogram of the linear fit slope, the relative error, and the correlation coefficient between GEN and OBS for the test cases. The relative error is defined as $\text{RMSE}(I_{\text{GEN}}, I_{\text{OBS}})/\text{average}(I_{\text{OBS}})$.

from SDO/AIA data in the future. This method is also useful for the modeling and image reconstruction of radio observation in other wavelengths. The results can support further study of the relationship between the microwave and EUV emission.

Acknowledgements We thank the Nobeyama Radioheliograph (NoRH) and the SDO/AIA science team. NoRH is operated by the NAOJ/Nobeyama Solar Radio Observatory AJOS, and SDO/AIA is developed and operated by NASA. This work was supported by the National Natural Science Foundation of China (Grant Nos. 41974199 and 41574167) and the B-type Strategic Priority Program of the Chinese Academy of Sciences (XDB41000000). We would like to acknowledge Drs. Masumi Shimojo and Satoshi Masuda from NAOJ, Dr. Tan Baolin from NAOC for help in delivering the NoRH data.

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