Dynamo saturation in rapidly rotating solar-type stars

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Abstract The magnetic activity of solar-type stars generally increases with stellar rotation rate. The increase, however, saturates for fast rotation. The Babcock-Leighton mechanism of stellar dynamos saturates as well when the mean tilt angle of active regions approaches ninety degrees. Saturation of magnetic activity may be a consequence of this property of the Babcock-Leighton mechanism. Stellar dynamo models with a tilt angle proportional to the rotation rate are constructed to probe this idea. Two versions of the model - treating the tilt angles globally and using Joy's law for its latitude dependence - are considered. Both models show a saturation of dynamogenerated magnetic flux at high rotation rates. The model with latitude-dependent tilt angles also shows a change in dynamo regime in the saturation region. The new regime combines a cyclic dynamo at low latitudes with an (almost) steady polar dynamo.

Key words: dynamo — stars: activity — stars: rotation — Sun: activity

1 INTRODUCTION

Sun-like stars are expected to host hydromagnetic dynamos generating magnetic fields in their external convection zones. This expectation is supported by the observed correlation of stellar magnetic activity with rotation rate. The physical reason for the correlation is the key role played by the rotation in dynamos (Parker 1979). On the Sun, chromospheric Ca II emission and coronal X-ray emission are correlated with magnetic fields. The relative Ca II and X-ray luminosities are, therefore, accepted as measures of stellar magnetic activity. Chromospheric (Noyes et al. 1984; Saar & Brandenburg 1999) and coronal (Vilhu 1984; Vilhu & Walter 1987; Pizzolato et al. 2003; Wright et al. 2011) activities generally increase with stellar rotation rate.

The increase in X-ray emission, however, saturates for Rossby numbers $\text{Ro} \lesssim 0.1$; $\text{Ro} = P_{\text{rot}}/\tau_{\text{c}}$ is the ratio of the rotation period to convective turnover time. Coronal activity stops increasing with sufficiently rapid rotation (Wright et al. 2011). Saturation in chromospheric activity, though less pronounced, can also be seen in figure 6 of Noyes et al. (1984). The observed saturation is an important clue for the dynamo theory of stellar activity. It indicates that dynamos do not produce stronger magnetic fields when the rotation rate of a star increases beyond a certain limit. A conventional explanation for dynamo saturation is, however, still lacking.

Literature on stellar dynamos is vast. Brandenburg et al. (1994), Jouve et al. (2010) and Işık et al. (2011) constructed dynamo models for stars with different rotational velocities but did not consider the saturation problem. Karak et al. (2014) discussed the possibility that a change in the direction of magnetic buoyancy from radial to parallel to the rotation axis as the rotation rate increases

(Choudhuri & Gilman 1987; Schuessler & Solanki 1992; Weber et al. 2011) may cause the dynamo saturation. They concluded that though the change in buoyant rise direction reduces the dynamo's efficiency, this effect does not suffice to explain the dynamo saturation. More recently, Blackman & Thomas (2015) suggested that an increase in differential rotation with angular velocity may cause the saturation. The life-time of convective eddies in rapidly rotating stars may be reduced due to distraction of the eddies by rotational shear thus leaving less time for the Coriolis force to affect the eddies and reduce dynamo efficiency. However, neither observations (Barnes et al. 2005; Collier Cameron 2007) nor modeling (Kitchatinov & Olemskoy 2012a) of stellar differential rotation show its considerable increase with rotation rate.

This paper concerns the possibility that dynamo saturation in rapid rotators is caused by saturation in the Babcock-Leighton (BL) mechanism of poloidal field generation. This mechanism was introduced by Babcock (1961) and first used in a dynamo model by Leighton (1969). It is related to the observed average tilt of bipolar groups of sunspots relative to the local parallel of latitude (Hale et al. 1919; Howard 1996). Due to the tilt, magnetic fields of solar active regions have on average a finite poloidal component, which contributes to the global poloidal field upon the sunspot groups decay. There is growing evidence for the operation of the BL mechanism on the Sun (Erofeev 2004; Dasi-Espuig et al. 2010; Kitchatinov & Olemskoy 2011b; Kitchatinov 2014). The BL-type dynamo model of Jiang et al. (2013) reproduces the basic correlations observed in solar activity. The BL mechanism can be expected to participate in stellar dynamos as well.

The contribution of the BL mechanism to the formation of global poloidal fields is proportional to the sine of the (averaged) tilt angle. The tilt is believed to result from the Coriolis force and therefore can be expected to increase with rotation rate. The BL mechanism obviously saturates when the tilt angle approaches $\pi/2$. The characteristic value of the tilt angle for the Sun is about 5° (Howard 1996). Assuming the angle to be proportional to the rotation rate, the tilt angle can reach 90° in a (solar mass) star rotating about 20 times faster than the Sun. This is roughly where the saturation in coronal activity of solar-type stars is observed (Wright et al. 2011).

To assess this idea quantitatively, we use stellar dynamo models, which only differ from a solar model by a modification of the α -effect (cf., e.g., Krause & Raedler 1980) of poloidal field regeneration. Two versions of the α -effect dependence on rotation rate are considered. In one of them, the dependence is treated globally by multiplying the α -effect by the factor of $\sin(\overline{\alpha}_{\odot}P_{\odot}/P_{rot})$ where $\overline{\alpha}_{\odot}$ and P_{\odot} are the averaged tilt angle and rotation period of the Sun, respectively, and P_{rot} is the rotation period of a star. In the other model, a similar procedure is applied to Joy's law of the latitude-dependent tilt angle. The second model shows a wider variety of dynamo behaviours but both show saturation of the generated magnetic flux for rapid rotation. The model's design is described in Section 2. The results of numerical computations for these models are discussed in Section 3. Section 4 summarises our main findings and concludes.

2 DYNAMO MODEL

The dynamo model of this paper differs little from those used before and, therefore, it is described here only briefly. The only difference with Olemskoy & Kitchatinov (2013) is in formulation of the α -effect. Other model ingredients like differential rotation, meridional flow and eddy transport coefficients remain unchanged. They may also depend on rotation rate but we avoid modifying anything else but the α -effect to see the consequence of saturation in the BL mechanism alone which is not disguised by other modifications.

2.1 Dynamo Equations

We consider the axisymmetric magnetic field B in a spherical shell modeling the external convection zone of a star,

$$\boldsymbol{B} = \boldsymbol{e}_{\phi}\boldsymbol{B} + \boldsymbol{\nabla} \times \left(\boldsymbol{e}_{\phi}\frac{\boldsymbol{A}}{r\sin\theta}\right),\tag{1}$$

where standard spherical coordinates (r, θ, ϕ) are used; e_{ϕ} is the azimuthal unit vector, B is the toroidal magnetic field, and A is the poloidal field potential. A similar expression for axisymmetric global flow V in a co-rotating frame can be written,

$$\boldsymbol{V} = \boldsymbol{e}_{\phi} r \sin \theta \Delta \Omega f(r, \theta) + \rho^{-1} \boldsymbol{\nabla} \times \left(\boldsymbol{e}_{\phi} \frac{\psi}{r \sin \theta} \right), \tag{2}$$

where $\Delta\Omega$ is the characteristic value of the angular velocity variation within the convection zone, f is the normalised differential rotation, ρ is density, and ψ is the stream function of the meridional flow.

The dynamo equations are written with normalised variables. Distance is measured in units of stellar radius R, time - in the diffusive units of $R^2 \eta_0^{-1}$, where η_0 is the characteristic value of the eddy diffusivity. The toroidal magnetic field is normalised to its 'equipartition' strength B_0 for which nonlinear feedback on the α -effect becomes essential. The poloidal field potential is normalised to $\alpha_0 B_0 R^3 \eta_0^{-1}$, where α_0 is the measure of the alpha-effect. Density is normalised to its value ρ_0 on the top boundary. The stream function is normalised to $\rho_0 R^2 V_0$, where V_0 is the amplitude of the surface meridional flow. The same notations are used for normalised variables as for their dimensional counterparts, except for the fractional radius x = r/R.

The normalised equation for the toroidal field of our dynamo model reads

$$\frac{\partial B}{\partial t} = \frac{\mathcal{D}}{x} \left(\frac{\partial f}{\partial x} \frac{\partial A}{\partial \theta} - \frac{\partial f}{\partial \theta} \frac{\partial A}{\partial x} \right) + \frac{R_{\rm m}}{x^2 \rho} \frac{\partial \psi}{\partial x} \frac{\partial}{\partial \theta} \left(\frac{B}{\sin \theta} \right) - \frac{R_{\rm m}}{x \sin \theta} \frac{\partial \psi}{\partial \theta} \frac{\partial}{\partial x} \left(\frac{B}{\rho x} \right) \\ + \frac{\eta}{x^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial(\sin \theta B)}{\partial \theta} \right) + \frac{1}{x} \frac{\partial}{\partial x} \left(\sqrt{\eta} \frac{\partial(\sqrt{\eta} x B)}{\partial x} \right),$$
(3)

where

$$\mathcal{D} = \frac{\alpha_0 \Delta \Omega R^3}{\eta_0^2} \tag{4}$$

is the dynamo number and

$$R_{\rm m} = \frac{V_0 R}{\eta_0} \tag{5}$$

is the magnetic Reynolds number for the meridional flow. The right-hand side of Equation (3) accounts for the toroidal field production by differential rotation, advection by the meridional flow, turbulent diffusion, and diamagnetic pumping due to the convective turbulence inhomogeneity (see Kitchatinov & Olemskoy 2012b, hereafter KO12, for more details). The square root of η appears in the last term to allow for diamagnetic pumping.

The poloidal field equation differs by representation of the α -effect but is otherwise identical to the solar dynamo model of KO12,

$$\frac{\partial A}{\partial t} = x \sin \theta F(\theta, P_{\text{rot}}) \int_{x_1}^x \hat{\alpha}(x, x') B(x', \theta) \, \mathrm{d}x' + \frac{R_{\text{m}}}{\rho x^2 \sin \theta} \left(\frac{\partial \psi}{\partial x} \frac{\partial A}{\partial \theta} - \frac{\partial \psi}{\partial \theta} \frac{\partial A}{\partial x} \right) + \frac{\eta}{x^2} \sin \theta \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial A}{\partial \theta} \right) + \sqrt{\eta} \frac{\partial}{\partial x} \left(\sqrt{\eta} \frac{\partial A}{\partial x} \right).$$
(6)

The first term on the right-hand side of this equation stands for the non-local α -effect of BL type. The kernel function $\hat{\alpha}(x, x')$ in this term differs considerably from zero only if x' is close to the inner boundary x_i and simultaneously x is close to the top boundary:

$$\hat{\alpha}(x,x') = \frac{\phi_{\rm b}(x')\phi_{\alpha}(x)}{1+B^{2}(x',\theta)},$$

$$\phi_{\rm b}(x') = \frac{1}{2} \Big\{ 1 - \operatorname{erf} \big[(x'-x_{\rm b})/h_{\rm b} \big] \Big\}, \qquad \phi_{\alpha}(x) = \frac{1}{2} \Big\{ 1 + \operatorname{erf} \big[(x-x_{\alpha})/h_{\alpha} \big] \Big\}, \tag{7}$$

where B^2 in the denominator represents the only nonlinearity of our model, which is the magnetic quenching of the α -effect, and erf is the error function. The values $x_b = x_i + 2.5h_b$ and $x_\alpha = 1 - 2.5h_\alpha$ ensure smoothness of the $\hat{\alpha}$ -function; $h_\alpha = 0.02$ and $h_b = 0.002$ in the computations of this paper. The α -effect in our model, therefore, describes the poloidal field generation near the surface from the toroidal field of the thin near-bottom layer. The factor $x \sin \theta$ in the first term on the right-hand side of (6) corresponds to the definition of the poloidal field potential A by Equation (1). The function $F(\theta, P_{\rm rot})$ accounts for the dependence of the α -effect on stellar rotation rate. This function will be defined in the next subsection.

The initial value problem for the system of Equations (3) and (6) is solved numerically. The initial field is a mixture of dipolar and quadrupolar fields, i.e., the equatorial symmetry is not prescribed. The superconductor boundary condition is imposed at the bottom boundary and a pseudo-vacuum condition (zero toroidal and radial poloidal fields) at the top.

2.2 Rotation Rate Dependence of the α -Effect

The poloidal part of the magnetic flux of a bipolar sunspot group is proportional to the sine of the group tilt-angle α . We, therefore, assume the BL type α -effect to be proportional to $\sin(\alpha)$ as well. The finite tilt in turn is believed to be caused by the Coriolis force action on the rising magnetic loops. The tilt angle is therefore expected to increase with rotation rate of a star. The α -effect changes little when $\sin(\alpha)$ passes through a broad maximum near $\alpha \simeq 90^{\circ}$ with an increasing rotation rate. This saturation of the α -effect may be the reason for the saturation in stellar magnetic activity.

The tilt angle in a solar mass star rotating with a period $P_{\rm rot}$ can be estimated as $\alpha = \alpha_{\odot}P_{\odot}/P_{\rm rot}$. Two models for the dependence of the α -effect on the stellar rotation rate will be considered. In the first model, we use a 'global' estimation of the tilt angle to write

$$F(\theta, P_{\rm rot}) = \cos\theta \sin^2\theta \frac{\sin(\overline{\alpha}_{\odot}P_{\odot}/P_{\rm rot})}{\sin\overline{\alpha}_{\odot}} - \text{Model I},$$
(8)

where $\overline{\alpha}_{\odot}$ is the mean value of the tilt angle for the Sun. The $\sin \overline{\alpha}_{\odot}$ was included as a denominator in this equation in order for the dynamo equations with *F*-function of Equation (8) to turn into our former solar model (KO12) at $P_{\rm rot} = P_{\odot}$. Then, the value of dynamo number $\mathcal{D} = 3.2 \times 10^4$ for which reasonable results for the Sun were obtained does not have to be changed. In the computations to follow, $\overline{\alpha}_{\odot} = 5^{\circ}$ (Howard 1996).

In the second model, Joy's law for the latitude dependence of the tilt angle (Hale et al. 1919) is allowed for. Dasi-Espuig et al. (2010) found $\alpha_{\odot} = (0.26 \pm 0.05)\lambda$ and $\alpha_{\odot} = (0.28 \pm 0.06)\lambda$ from sunspot data of the Mount Wilson and Kodaikanal observatories, respectively, where λ is latitude. Ivanov (2012) confirmed their results but found a somewhat larger proportionality factor of 0.38 ± 0.03 from the Pulkovo observatory database. Stenflo & Kosovichev (2012) inferred a still steeper dependence of $\alpha_{\odot} = (0.56 \pm 0.01) \sin \lambda$ from *MDI/SOHO* magnetograms. They also noted that $\sin \lambda$ is a natural choice for the fit function in Joy's law because the Coriolis force, presumably producing the tilts, varies as $\sin \lambda$ with latitude. The larger tilt angles from magnetograms are probably explained by the contribution of plages (Wang et al. 2015). As the BL type α -effect is more related to sunspots of active regions than to smaller magnetic features of magnetograms, we employ Joy's law in the form $\alpha_{\odot} = 0.3 \cos \theta$ to find

$$F(\theta, P_{\rm rot}) = \sin\left(0.3\cos\theta P_{\odot}/P_{\rm rot}\right) - \text{Model II}$$
(9)

for the *F*-function in Equation (6). As computations of the solar dynamo with such a profile of the α -effect have never been attempted before, we have to define the critical value of \mathcal{D} (Eq. (4)) for the onset of dynamo. The computed critical value for dipolar modes in the solar ($P_{\rm rot} = P_{\odot}$) model is $\mathcal{D}^{\rm d} = 6.63 \times 10^4 (D^{\rm q} = 7.21 \times 10^4 \text{ for modes of quadrupolar parity})$. The solar dynamo is probably

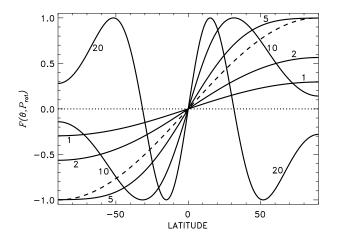


Fig.1 Latitudinal profiles of the α -effect (Eq. (9)) of Model II for different rotation rates. The lines are marked by the corresponding values of $P_{\odot}/P_{\rm rot}$. The often assumed $\cos \theta$ -profile is shown for comparison by the dashed line.

only slightly supercritical (see discussion in Karak et al. 2015). All computations in Model II were performed with $\mathcal{D} = 7 \times 10^4$, which is about 5% supercritical for the solar case.

Figure 1 shows latitudinal profiles of the α -effect (Eq. (9)) of Model II for several rotation rates. The profile of $\cos \theta$, often assumed in dynamo models, is shown for comparison. The α effect initially increases with rotation rate, but then saturates and even changes to a decrease at high latitudes for $P_{\rm rot} < P_{\odot}/5$. This is the reason for dynamo saturation in subsequent computations. Note the sign reversals in the alpha profile for $P_{\rm rot} = P_{\odot}/20$. The change of sign is important for interpreting the results of dynamo simulations for rapid rotators.

2.3 Other Model Ingredients

The differential rotation, meridional flow and diffusivity profile in this paper are the same as in Olemskoy & Kitchatinov (2013).

As mentioned in the Introduction, observations and theoretical modeling both suggest that differential rotation varies moderately with the rotation rate of a solar-type star of a given mass (Barnes et al. 2005; Collier Cameron 2007; Kitchatinov & Olemskoy 2012a). The same differential rotation specified after the approximation of Belvedere et al. (2000) for the helioseismological rotation law is used for all stars.

The eddy magnetic diffusivity varies little in the bulk of the solar convection zone but drops sharply with depth near its base. The diffusivity profile of our model mimics this behaviour:

$$\eta(x) = \eta_{\rm in} + \frac{1}{2}(1 - \eta_{\rm in}) \left[1 + \operatorname{erf}\left(\frac{x - x_{\eta}}{h_{\eta}}\right) \right].$$
(10)

Computations were performed for the following values of the parameters in this equation: $\eta_{in} = 10^{-4}$, $x_{\eta} = 0.74$ and $h_{\eta} = 0.02$.

Figure 2 shows the diffusivity profile for these parameter values together with the functions $\phi_{\rm b}$ and ϕ_{α} of Equation (7) defining the alpha-effect. The diffusivity drops four orders in magnitude near the bottom boundary. A non-uniform numerical grid with very small grid spacing near the bottom was used to resolve this sharp variation.

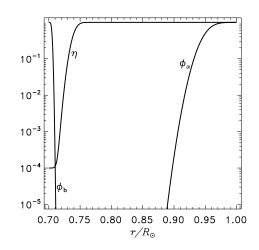


Fig. 2 Profiles of diffusivity and the kernel functions (7) of the non-local α -effect of Eq. (6) used in our dynamo models.

Single-cell meridional circulation with poleward flow on the top and return equatorward flow near the bottom is prescribed (see fig. 3 and eq. (13) in Olemskoy & Kitchatinov 2013). The value of $R_{\rm m} = 10$ for the Reynolds number (Eq. (5)) is used in the computations, which corresponds to the flow amplitude $V_0 \simeq 15 \,\mathrm{m \, s^{-1}}$ and background diffusivity $\eta_0 \simeq 10^9 \,\mathrm{m^2 \, s^{-1}}$. With this relatively low Reynolds number, the meridional flow in the bulk of the convection zone is not significant. Only the flow near the bottom where diffusion is low (Fig. 2) is important for magnetic field dynamics (Hazra et al. 2014). The same value of $\eta_0 \simeq 10^9 \,\mathrm{m^2 \, s^{-1}}$ was used to convert dimensionless time into physical units.

As the BL α -effect is related to surface active regions, we illustrate toroidal fields of dynamo models by butterfly diagrams for the same near-bottom toroidal flux,

$$\mathcal{B}(\theta) = \sin \theta \int_{x_{i}}^{1} \phi_{b}(x) B(x,\theta) \, \mathrm{d}x \,, \tag{11}$$

to which the α -effect of Equations (6) and (7) is proportional. Note that the weight function ϕ_b of Figure 2 differs considerably from zero in a thin near-bottom layer only. Equation (11) therefore represents the near-bottom toroidal flux. The factor $\sin \theta$ in Equation (11) accounts for the dependence of the length of toroidal flux-tube on latitude. The probability of the production of spots is assumed to be proportional to this length. The unsigned total near-bottom flux,

$$f_{\rm m} = \iint_{x_{\rm i}\,0}^{1} \sin\theta \, x \, \phi_{\rm b}(x) \left| B(x,\theta) \right| \, \mathrm{d}x \, \mathrm{d}\theta \,, \tag{12}$$

is used as a proxy for the overall magnetic activity.

Dynamo computations started from a weak poloidal field with a mixed equatorial parity. Upon several diffusion times, initial field growth saturates. The results of the next section correspond to these saturated dynamo regimes.

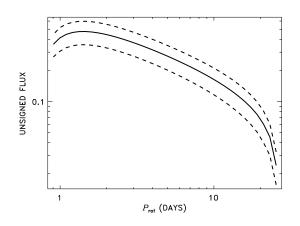


Fig. 3 Dependence of unsigned flux (Eq. (12)) on rotation period for Model I. The dashed lines show maximum and minimum values of the flux in the dynamo cycles. The solid line shows the median value (half-sum of maximum and minimum).

3 RESULTS AND DISCUSSION

In all runs, the dynamo fields eventually approached dipolar parity. This seems to be a common feature of dynamo models with relatively large diffusivity in the bulk of the convection zone (Chatterjee et al. 2004; Jiang et al. 2007; Hotta & Yokoyama 2010). The global magnetic field of the Sun is also close to dipolar parity (Stenflo 1988). All the simulated dynamos are cyclic.

3.1 Model I

Observational statistics of stellar activity usually do not cover epochs comparable to expected activity cycles. It is therefore not clear for which phase of the dynamo cycles the fluxes (Eq. (12)) should be estimated.

Figure 3 shows how the maximum, minimum and median values of the fluxes depend on the rotation period.

The main feature of this plot is that the $f_{\rm m}$ stops increasing with rotation rate for small $P_{\rm rot}$. Observations of stellar activity show its saturation at Rossby numbers 10–20 times smaller than the solar value (fig. 2 of Wright et al. 2011). Stellar structure in our computations is not varied (because the Sun remains the only star for which the tilt angles are measured). The Rossby number is, therefore, proportional to the rotation period. The position of the saturation region in Figure 3 roughly agrees with observations. This figure also shows a decline in $f_{\rm m}$ for still shorter $P_{\rm rot}$. It is not clear whether the decline is real or not because observational statistics have considerable scatter and usually do not distinguish spectral types (cf., however, Pizzolato et al. 2003).

Coronal activity data for moderately rotating stars (Ro > 0.2) are customarily fitted by the power law (Pallavicini et al. 1981; Wright et al. 2011),

$$L_{\rm X} \propto {\rm Ro}^{-\gamma}$$
. (13)

The slope of the plot in Figure 3 is not constant. However, it varies little in the region of $3 < P_{\rm rot} < 10 \,\text{d}$. The slope δ , defined in the same way as in Karak et al. (2014),

$$f_{\rm m}^2 \propto P_{\rm rot}^{-\delta}$$
, (14)

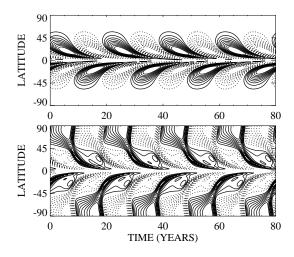


Fig. 4 Time-latitude diagram of Model I for $P_{\text{rot}} = 1$ d. *Top panel:* near-bottom toroidal flux of Equation (11). *Bottom panel:* radial magnetic field on the surface.

is about $\delta \simeq 1.5$ in this region. Though our model is designed to qualitatively explain activity saturation in rapid rotators and not to achieve quantitative agreement with observations, a preliminary comparison is tempting. If γ is taken to be equal to its canonical value of 2, then our model would mean that L_X is proportional to f_m to the power of 2.7, which is somewhat larger than the power of 2 expected for L_X being proportional to magnetic energy. The power index is still larger $(2\gamma/\delta \simeq 3.6)$ for the value of $\gamma = 2.7$ of Wright et al. (2011).

Measurements of large-scale stellar magnetic fields are most relevant to predictions of dynamo models. The measurements are provided by the Zeeman-Doppler imaging (ZDI) technique (Donati & Brown 1997). Though statistics of ZDI for main-sequence dwarfs are not vast (about 100 stars), the dependence of the large-scale fields on rotation rate has been estimated by Vidotto et al. (2014). Their results generally confirm the proportionality of X-ray luminosity to the square of unsigned magnetic flux Φ_V of large-scale fields. Vidotto et al. (2014) also found the power law $\Phi_V \propto \text{Ro}^{-1.19\pm0.14}$ for Ro > 0.1 and saturation of Φ_V at smaller Ro. We have to conclude that our dynamo model underestimates the power index δ of Equation (14).

Figure 4 shows the butterfly diagram for the rapid rotator with $P_{\rm rot} = 1$ d. It is quite similar to the solar model (KO12). Field patterns computed for different rotation rates are qualitatively similar and differ mainly in the field amplitude. This is because only the α -effect in our model depends on rotation rate. The cycle period for Figure 1 is about 10 yrs. The cycle period changes little with rotation rate. This is because the meridional flow does not vary. The cycle period is controlled by the flow circulation time in advection-dominated dynamos (Charbonneau 2010; Choudhuri 2011).

3.2 Model II

Model II with the α -effect of Equation (9) has not been applied to the Sun before. We therefore consider the solar case first.

Figure 5 shows the time-latitude diagram computed for $P_{\text{rot}} = P_{\odot}$. The polar branch of the poloidal field is lacking but otherwise the diagram is satisfactory. The cycle period in Figure 5 is about 9.6 years. The cycle period varies little with rotation rate (until a new dynamo regime with

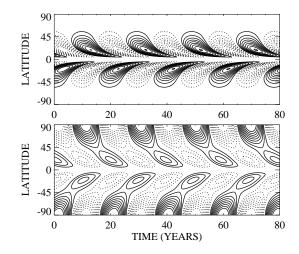


Fig. 5 Time-latitude diagram of Model II for the solar model. Top and bottom panels have the same meaning as in Fig. 4 but are computed for the α -effect of Eq. (9) and with $P_{\rm rot} = P_{\odot}$.

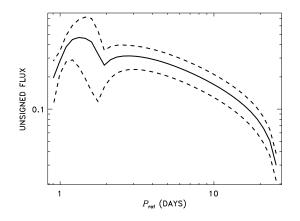


Fig. 6 Same as Fig. 3 but for Model II. The two dashed lines and solid line show the maximum and minimum values of $f_{\rm m}$ (Eq. (12)) in dynamo cycles and their median value, respectively.

a not well defined period emerges for rapid rotation). The reason is the same as for Model I: the meridional flow is kept constant.

Figure 6 shows the dependence of unsigned flux (Eq. (12)) on rotation rate. The dependence is not as smooth as in Model I but generally shows a saturation as well at $P_{\rm rot} \lesssim 3$ d. The power index of Equation (14), $\delta \simeq 1.3$ (at $P_{\rm rot} \simeq 7$ d), agrees with the computations of Karak et al. (2014).

The kink in the dependence at rotation periods slightly below 2 d signifies a change in the dynamo regime. The new regime is illustrated by the time-latitude diagram of Figure 7. This figure shows field reversals at low latitudes but high-latitude fields do not change sign. Polar fields oscillate about a non-zero mean value.

The following interpretation for this behaviour can be suggested. The positive α -effect (in the northern hemisphere) of solar-type dynamos generates a poloidal field from the toroidal one, and the

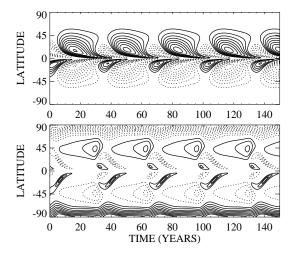


Fig. 7 Same as Fig. 5 but for $P_{\rm rot} = 1$ d. The fields at high latitudes oscillate about non-zero mean values.

new poloidal field has an opposite sign compared to the old poloidal field from which the toroidal field is wound by the (solar-type) differential rotation. Sign reversals of magnetic fields, therefore, take place and the dynamo is cyclic. If the α -effect were negative, a new poloidal field with the same sign as the old one would be generated and steady dynamos could be expected.

Figure 1 shows sign reversals of the α -effect in the northern hemisphere for sufficiently rapid rotation ($P_{\rm rot} < 2.2 \,\text{d}$). The α -value remains positive near the equator but changes to negative at high latitudes. When the polar region with negative α is sufficiently broad, a new regime which combines cyclic equatorial with steady polar dynamos sets in.

4 CONCLUSIONS

The possibility for the saturation of magnetic activity observed for rapidly rotating solar-type stars (Vilhu 1984; Pizzolato et al. 2003; Wright et al. 2011) being related to the properties of the BL mechanism for magnetic field generation was discussed. This mechanism naturally saturates when the mean tilt angle approaches 90°. Computations with dynamo models generally support this idea.

Two dynamo models were considered. The tilt angle dependence on rotation rate was treated globally in Model I of Equation (8). Model II of Equation (9) employed Joy's law for latitude dependence of the tilt angles. Both models show saturation of dynamo-generated magnetic flux at high rotation rates.

Model II is probably more realistic and it demonstrates more variable behaviour. As rotation rate increases, the α -effect first saturates, then decreases and can even change sign if the tilt angle exceeds 180°. In Model II, this happens earlier at higher latitudes (Fig. 1). This leads to a change in dynamo regime with increasing rotation rate. The new regime emerging at high rotation rates combines field reversals at low latitudes with oscillations about a non-zero mean value without a change of sign in the polar fields (Fig. 7). Magnetic energy is not sensitive to the field sign and, therefore, shows doubly periodic variations in this dynamo regime. The double cycles have indeed been observed in solar-type stars with relatively low Rossby numbers (Saar & Brandenburg 1999).

Two versions of the α -effect are currently discussed for the Sun: the BL mechanism and the α -effect of convective turbulence by Parker (1955). Evidence for participation of the BL α -effect in the solar dynamo is growing (Erofeev 2004; Dasi-Espuig et al. 2010; Olemskoy et al. 2013). Interpretation of dynamo saturation in rapidly rotating solar-type stars adds one more argument to

this line. This is not only because this effect saturates for rapid rotation. The α -effect of convective eddies should saturate as well when the eddies are twisted by about 90° (the saturation is somehow missed by quasi-linear theories of the α -effect). However, the saturation of magnetic activity in the models based on the BL mechanism is found at rotation rates about 20 times the solar value where observations also indicate it occurs in solar-mass stars. A combined action of both effects is possible (Passos et al. 2014) but the BL mechanism seems to be dominant.

Only the α -effect depends on rotation rate in our model. Other parameters can also depend on $P_{\rm rot}$ but were kept constant to see the exclusive consequences of α -effect saturation. Work combining the model for (variable) stellar differential rotation and meridional flow (Kitchatinov & Olemskoy 2011a) with a dynamo model is currently in progress.

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